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APPENDIX 1

```
void sw ()
            (
 5
                                                            /* instruction
            #define iw = 12;
                                                            width */
                                                            /* memory width */
            \#define mw = 3:
                                                            /* push constant */
             #define CONST = 0
                                                            /* push variable */
             \#define LOAD = 1
10
                                                             /* push address */
             \#define GLOBAL = 2
                                                            put a character along the
             #define PUTCHAR, = 15 /*
                                                            standard output channel*/
                                                            get a character from the
             #define GETCHAR = 16 /*
                                                            standard input channel */
15
             •••
             rom program []
             #include "prog.o"): ram stack[1\llmw] with dualport = 1];
20
             ram memory[1<mw] unsigned iw PC, ir, tos;
             unsigned mw sp;
             do par it = program[pc]: PC = PC + 1;
                                                               /* save top of
             tos = stack[sp-1];
25
                                                               stack to avoid
                                                               two ram accesses
                                                               in one cycle
                                                               */
30
             switch (ir)
             case
             CONST par
                    stack[sp] = program[pc];
                    sP = sP+1:
35
                    PC = Pc+1:
                    break;
             case LOAD
                    stack[sp-1] = memory[tos<-mw];
40
                    break;
                                                                /* unknown opcode */
             case STOP break; default:
             while (1) delay;
             ] while (ir != STOP);
45
```

]

Register transfer level description of simple processor

5

APPENDIX 2

APPENDIX 3

CALCULATION PROCESS

```
5
     /*
      * Channel communicating object positions
      */ chap unsigned 17 position;
     /*
10
      * Channel communicating segment information
      chanout unsigned 9 segment;
      /*
      * Channel communicating button information
15
      chanin unsigned 2 buttons;
      * Overall par
20
      */ par
             * Mass motion
25
                 * Positions of each mass, 9+8 fixed point
                 unsigned 17 p0, p1, p2, p3, p4, p5, p6, p7;
30
                 * Velocity of each mass, 9+8 fixed point
                 int 17 vl, v2, v3, v4, v5, v6, v7; '
35
                 * Accelerations of each mass, 9+8 fixed point
                 int 17 al, a2, a3, a4, a5, a6, a7;
40
                 * Sutton status
                 unsigned 2 button status;
                 * Initial setup of positions
45
```

```
p0 = 65536;
                         p1 = 65536;
                         p2 = 65536;
                         p3 = 65536;
       5
                         p4 = 65536;
                         p5 = 65536;
                         p6 = 65536
                         p7 = 65536
      10
                          * Forever
                          */
                         while (1)
      15
                            {
                           /*
                             * Send successive positions down position channel
Com the free property from the first offer
      20
                           send(position, p0);
                           send(position, p1);
                           send(position, pl);
                           send(position, p2);
                           send(position, p2);
                           send(position, p3);
      25
                           send (position, p3);
=
                           send(position, p4);
ķæ
                           send(position, p4);
The Hall Me thin the
                           send(position, p5);
      30
                           send(position, p5);
                           send(position, p6);
                           send(position, p6);
                           send(position, p7);
      35
                            * Update positions according to velocities
                             */
                           pl + (unsigned 17)vl;
                           p2 + (unsigned 17)v2;
      40
                           p3 + (unsigned 17)v3;
                           p4 + (unsigned 17)v4;
                           p5 + (unsigned 17)v5;
                           p6 + (unsigned 17)v6;
                           p7 + (unsigned 17)v7;
      45
                             /*
```

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```

```
* Update velocities according to accelerations
                       */
                     v1 += a1 - (v1 > 6);
                     v2 += a2 - (v2 > 6);
 5
                     v3 += a3 - (v3 > 6);
                     v4 += a4 - (v4 > 6);
                     v5 += a5 - (v5' > 6);
                     v6 += a6 - (v6 > 6):
                     v7 += a7 - (v7 > 6);
10
                     /*
                       * Set accelerations according to relative positions
                      */
                     a1 = (int 17)(((p2 > 8) - (p1 > 8)) + ((p0 > 8) - (p1 > 8)));
15
                     a2 = (int 17)(((p3 » 8) - (p2 » 8)) + ((p1 » 8) - (p2 » 8))):
                     a3 = (int 17)!!(p4 \gg 8) - (p3 \gg 8)) + ((p2 \gg 8) - !p3 \gg 8)));
                     a4 = (int 17)(((p5 » 8) - (p4 » 8)) + ((p3 » 8) - (p4 » e > );
                     a5 = (int 17)((!p6 » 8) - (p5 » 8)) + ((p4 » 8) - (p5 » 8)));
                     a6 = (int 17)(((p7 \gg 8) - (p6 \gg 8)) + ((p5 \gg 8) - (p6 \gg e >);
20
                     a7 = (int 17)((p6 \gg 8) - (p7 \gg 8));
                     /*
                      * Get button information
25
                     receive(buttons, button status);
                      * Fix top point according to buttons
                      */ if (button status & 1)
30
                        p0 = 65536 - 16384;
              else
                        if (button status & 2)
                          p0 = 65536 + 16384;
35
              else
                          p0 = 65536;
40
                )
                 * nine drawing
45
```

```
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```

```
* Positions of previous and next massess positions
                 unsigned 17 prev .pos, next pos, curr pos;
 5
                   * Which line of interpolation
                 unsigned char line;
                  * Forever
10
                   */
                 while (1)
                     * Receive previous mass position
15
                    receive (position, prev posy;
                    curr pos = prev pos;
                     * Read next mass position
20
                    receive(position, next posy;
                     * Do 64 lines of interpolation
                    for (line = 0; line != 64; line++)
25
                      (
                          * Send start position of segment
                         send(segment, curr pos » 8);
                                                         /**width adjustment:17 along
30
                                                          channel of width 9 so takes bottom 9
                                                          bits*/
                          * Move by appropriate amount (1/64 total change)
35
                         curr pos + (unsigned 17)(((int 17)next pos -
                                                    (int 17)prev pos) » 6);
                         /*
40
                          * Send end position of segment
                         send(segment, curr pos » 8):
                    )
               )
45
      )
```

```
DISPLAY PROCESS
 5
     /* standard includes */
                 #include "hammond.h"
           #include "syncgen.h"
            #include "stdlib.h"
           #include "parallel.h"
10
     * Segment information channel */ chap segment;
15
     * Button information channel */
     chan buttons:
     * Include dash generated stuff */
20
     #include "handelc.h"
     * Main program */
25
     void main() (
     * Scan positions
      */ unsigned sx, sy;
30
      * Vdeo output register
     unsigned 1 video;
35
      * Video output bus
     interface bus out() video out(Visible(sx, sy)?
     (video ? (unsigned 12)Oxfff: 0) 0) with video spec;
40
     #ifndef SIMULATE
      * Left button input bus
45
     interface bus in (unsigned 1) button_left()
```

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with button white spec;

```
/*
      * Right button input bus
 5
      */
              interface bus in(unsigned 1) button right()
                 with button_black spec;
            #endif
10
      /*
                  Overall par
     */ par {
                     * VGA sync generator
15
                     */
                    SyncGen(sx, sy, hsync pin, vsync pin);
20
                       Dash generated hardware
                   hardware();
                     * Run-length decoder
                     */
25
                    /*
                     * Segment start and end positions
                    unsigned start, end;
30
                    /*
                     * Forever
                     */
                    while (1)
35
                       {
                         while (sy != 448)
                             * Read segment information
                           segment? start;
40
                           segment? end;
                             * Get in the right order
                           if (start > end)
45
                               {
```

```
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```

```
par
                                   {
     end = start;
5
     start = end;
     )
      * Make at least 1 pixel visible
10
      */
     if (start = end)
                              end++;
15
      /*
                             * Wait
      */
                           while (sx != 0)
                              delay;
20
                             * Draw a scanline worth
                           while (sx !=512)
                                i\hat{f}((sx <- 9) >= start && (sx <- 9) < end)
25
                                   video = 1;
                                 else
                              video = 0;
                              )
30
                           * Communicate button status
             #ifdef SIMULATE
35
                         buttons!1;
             #else
                          buttons! button left.in @ button right.in;
             #endif
                           * Wait
40
                         while (sy != 0)
                            delay;
                       )
45
```

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